



ExaScience Lab
Intel Labs Europe



EXASCALE COMPUTING

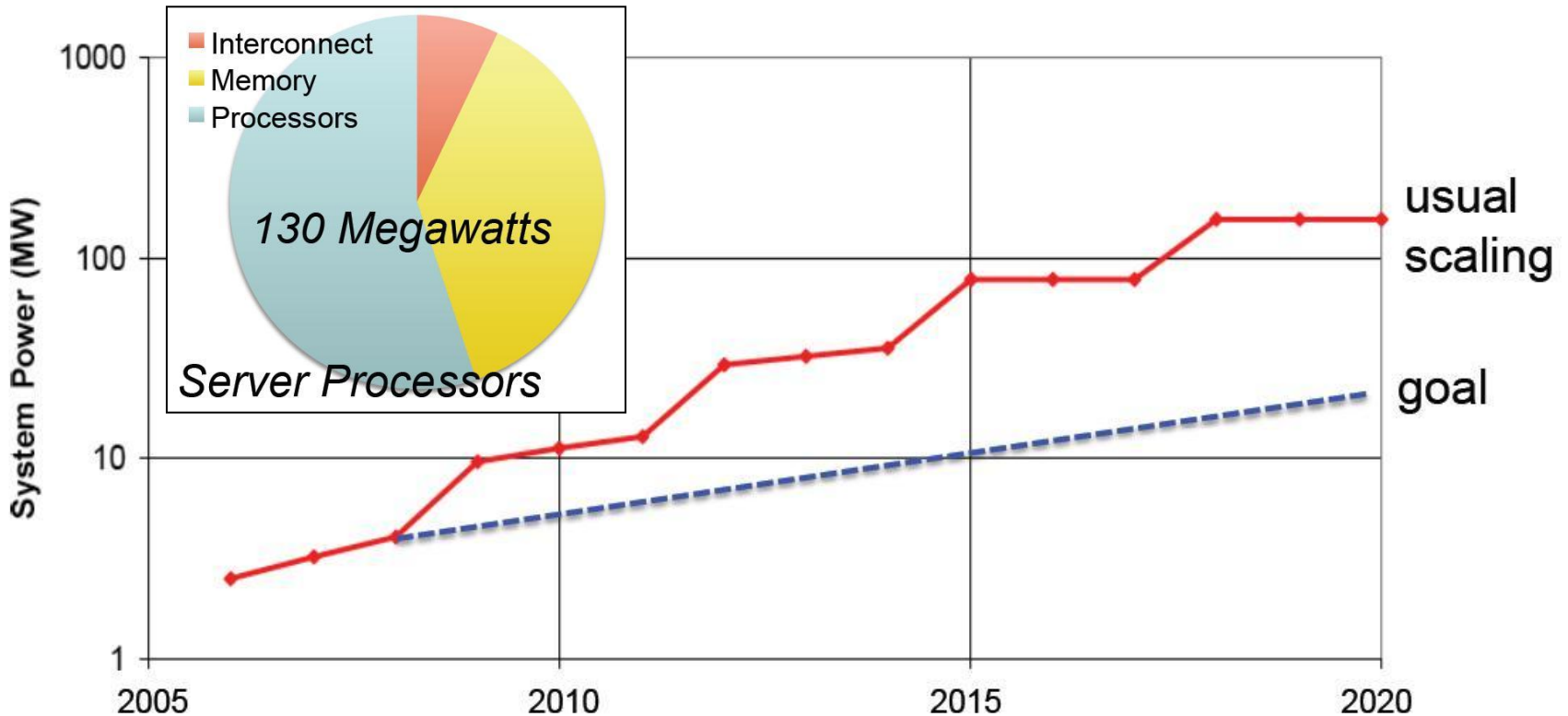
Using Fast and Accurate Simulation to Explore Hardware/Software Trade-offs in the Multi-Core Era

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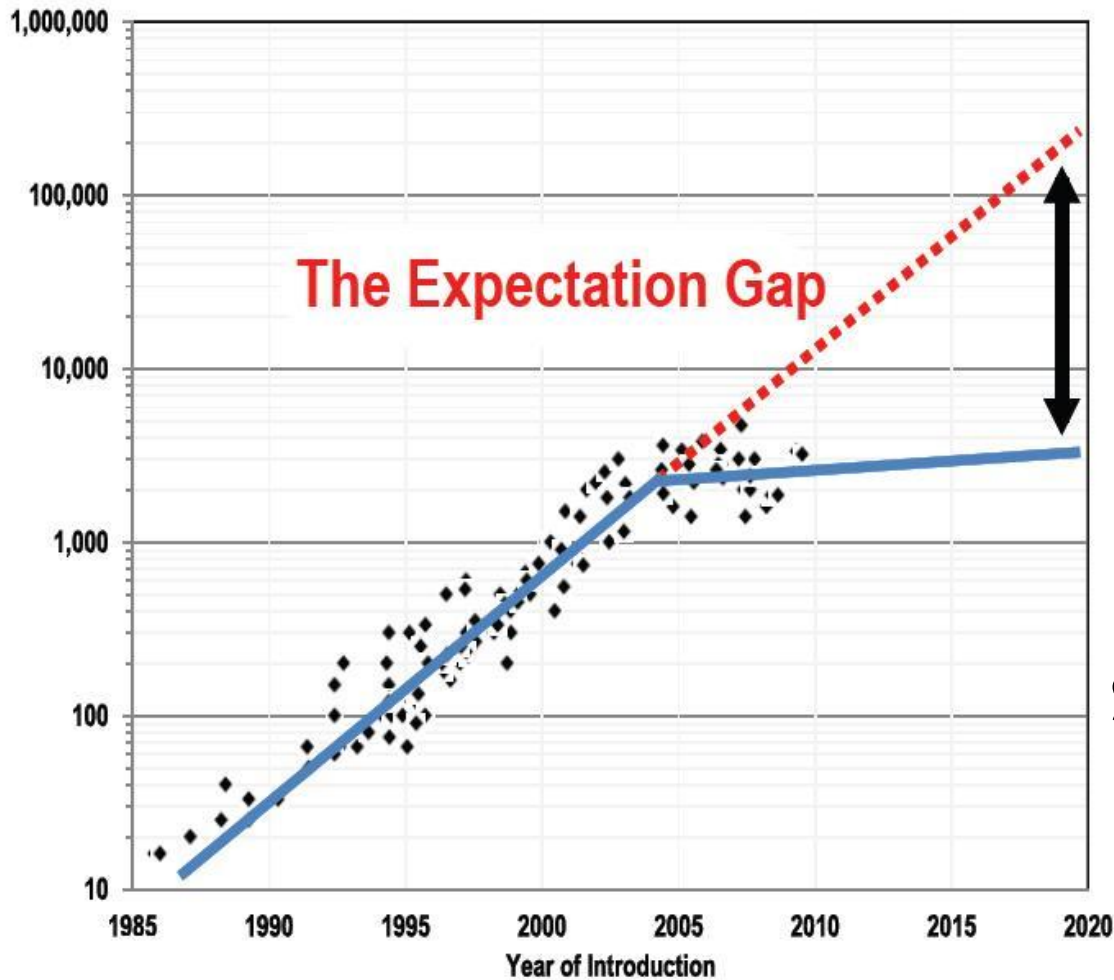
HPC Power Challenges



- #1 on TOP500 (K,Japan) consumes 9.9MW @ 8.1 Petaflops
- Exascale goal: 2018, 20MW @ 1,000 Petaflops
 - 2x power, 100x performance (beyond Moore's law)

Source: Yalick, EXADAPT 2011

HPC Performance Challenges



Single-core performance is not keeping pace

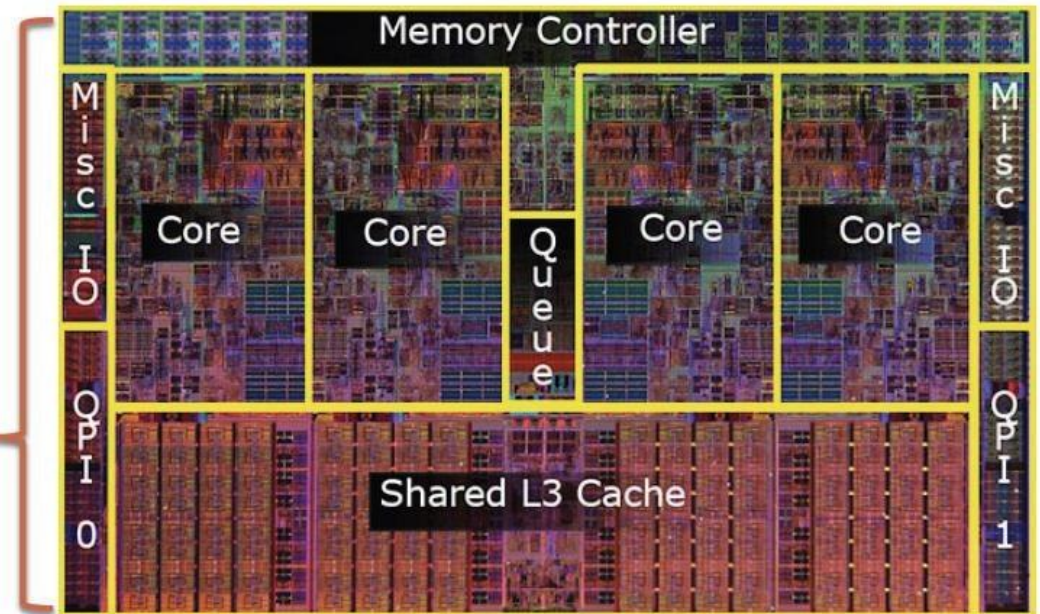
Source: Yalick, EXADAPT 2011

Current Microprocessor Trade-offs



Cell phone processor
(0.1 Watt, 4 Gflop/s)

Server processor
(100 Watts, 50 Gflop/s)



Is there something in-between?

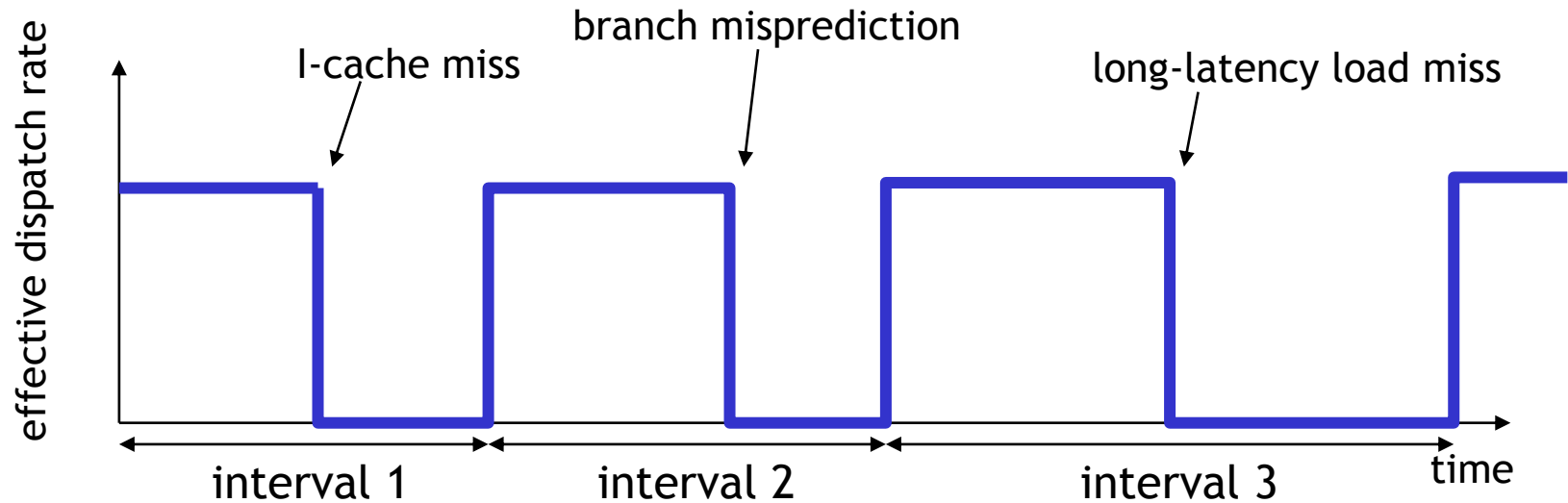
Exascale Challenges

- Future systems will be diverse
 - Varying processor speeds
 - Varying failure rates for different components
 - Homogeneous applications become heterogeneous
- Software and hardware solutions are needed to solve these challenges
 - Handle heterogeneity (reactive load balancing)
 - Be fault tolerant
 - Improve power efficiency at the algorithmic level (extreme data locality)
- Hard to model accurately with analytical models

Exascale challenges require fast and accurate simulation

- Fast and accurate simulation
 - Sniper = Interval Model + Graphite framework
 - Parallel simulator scales with the number of simulated cores
 - Available at <http://www.snipersim.org>
- Key Questions
 - What is the right level of abstraction?
 - When can we use these abstraction models?
- Key Capabilities
 - Model all (relevant) aspects of hardware accurately (enough)
 - Allow application designers to start exploring hardware-software interactions

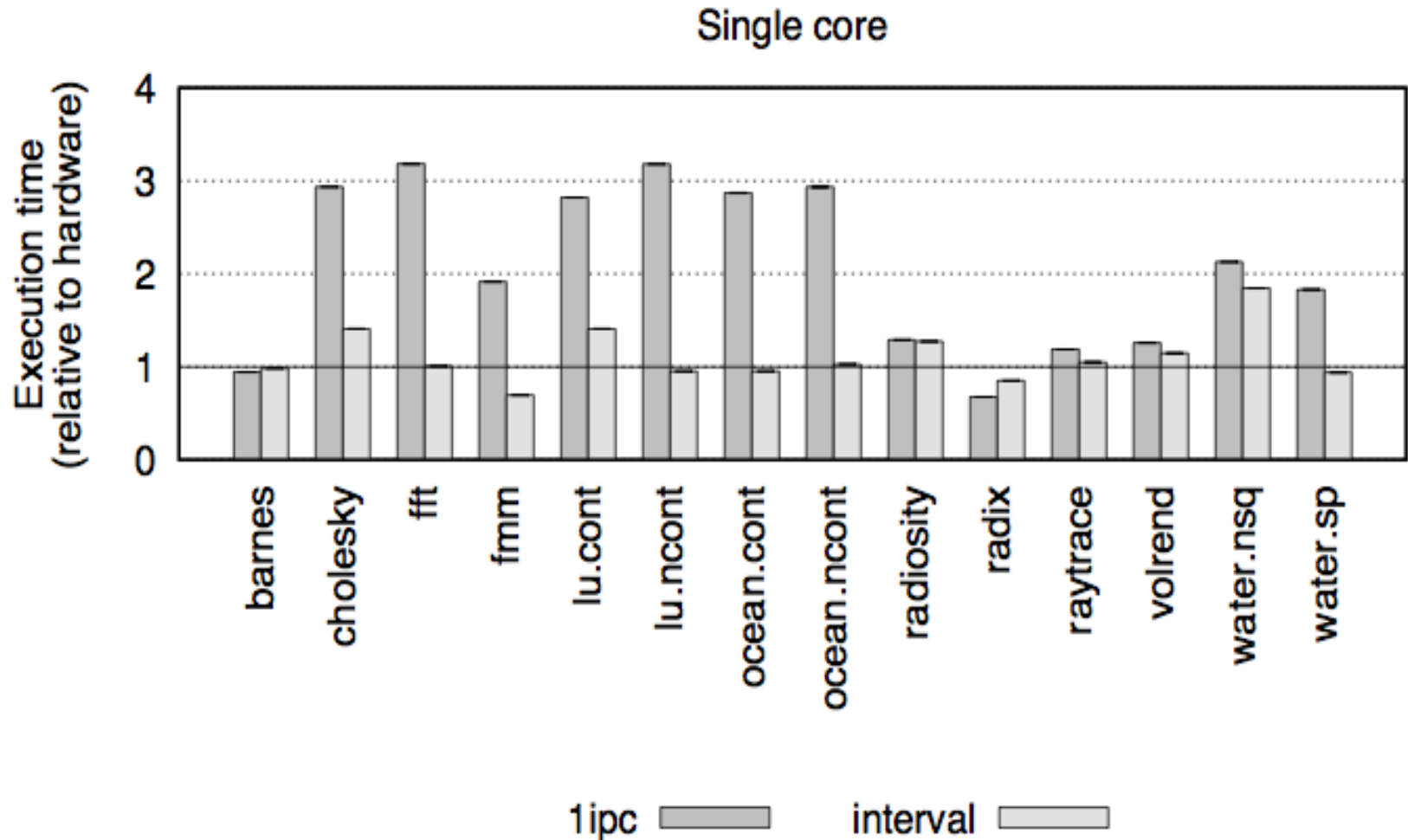
Interval simulation: out-of-order core performance model at in-order simulation speed



D. Genbrugge et al., HPCA'10
S. Eyerman et al., ACM TOCS, May 2009
T. Karkhanis and J. E. Smith, ISCA'04, ISCA'07

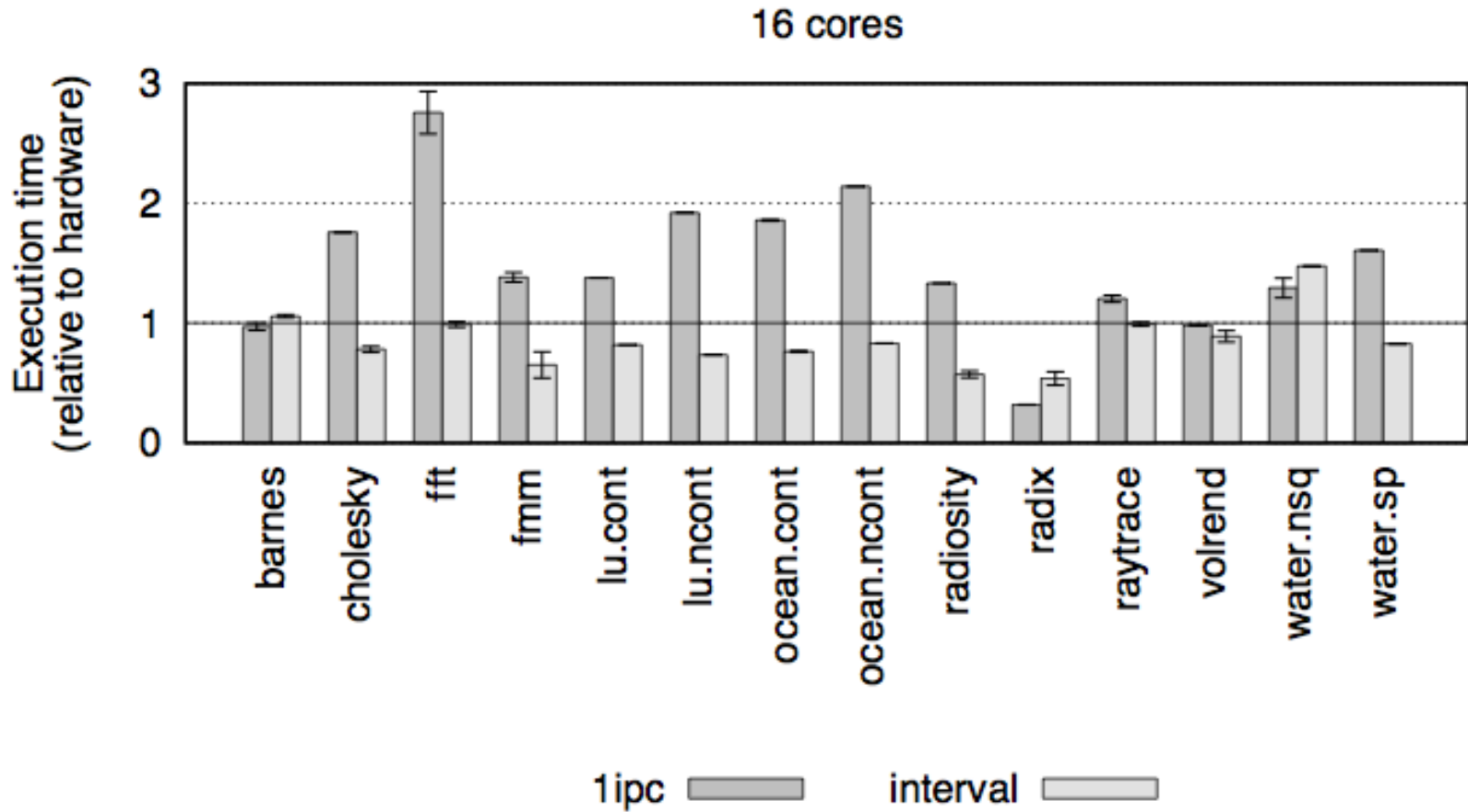
Simulator accuracy

single core: 20% avg abs error

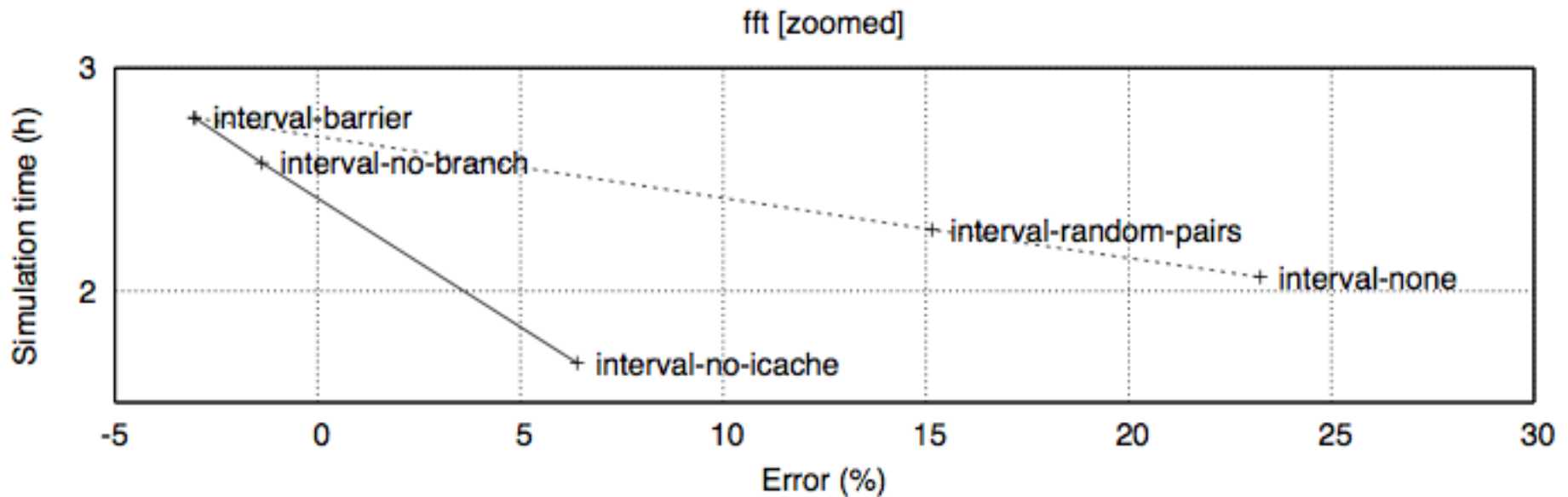


Simulator accuracy

16 cores: 24% avg abs error vs. 60% avg error for one-IPC

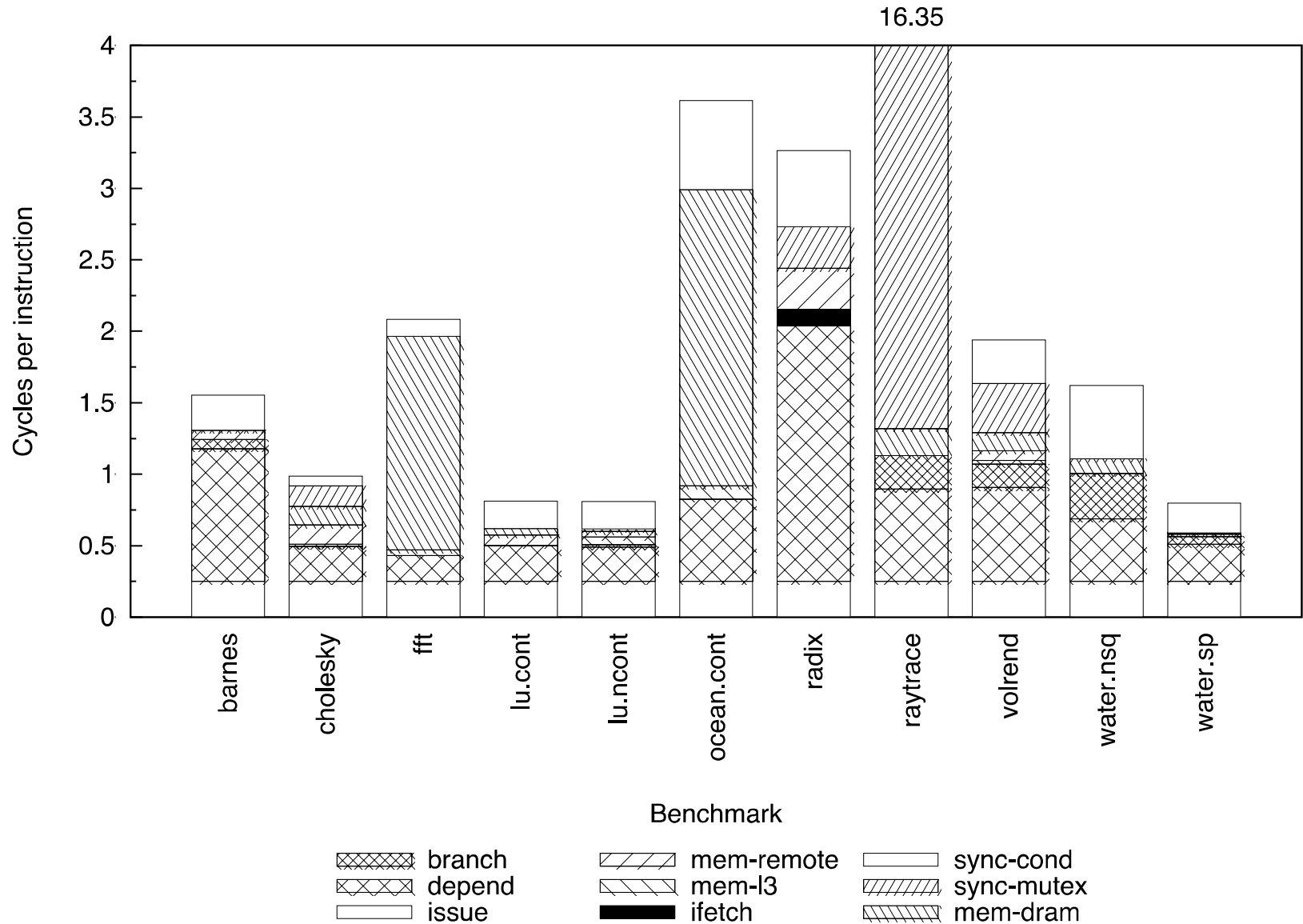


Synchronization: speed vs. accuracy trade-off



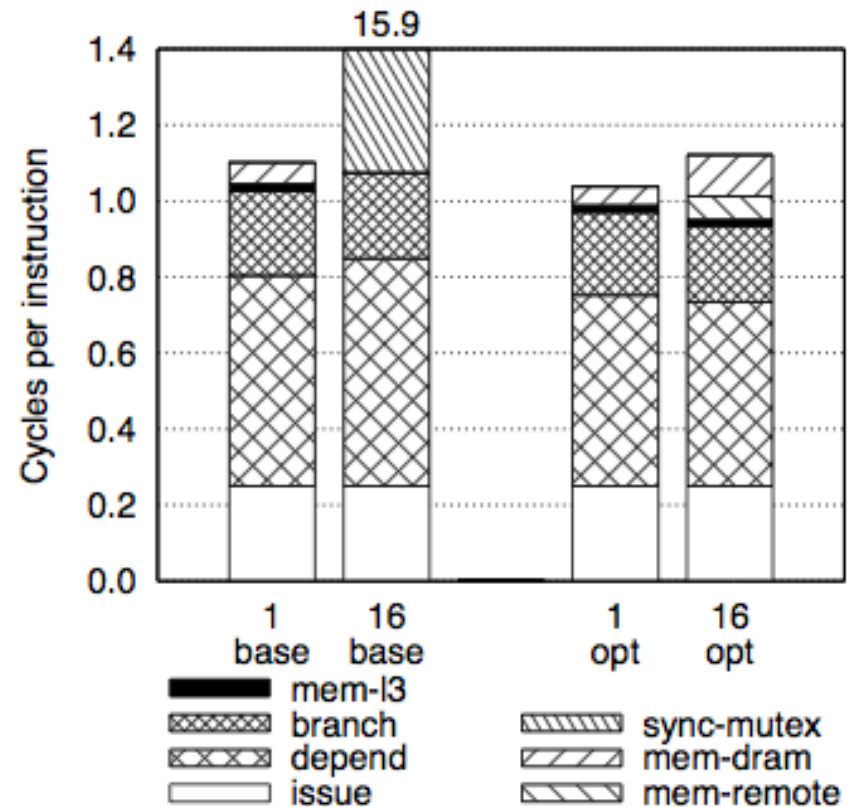
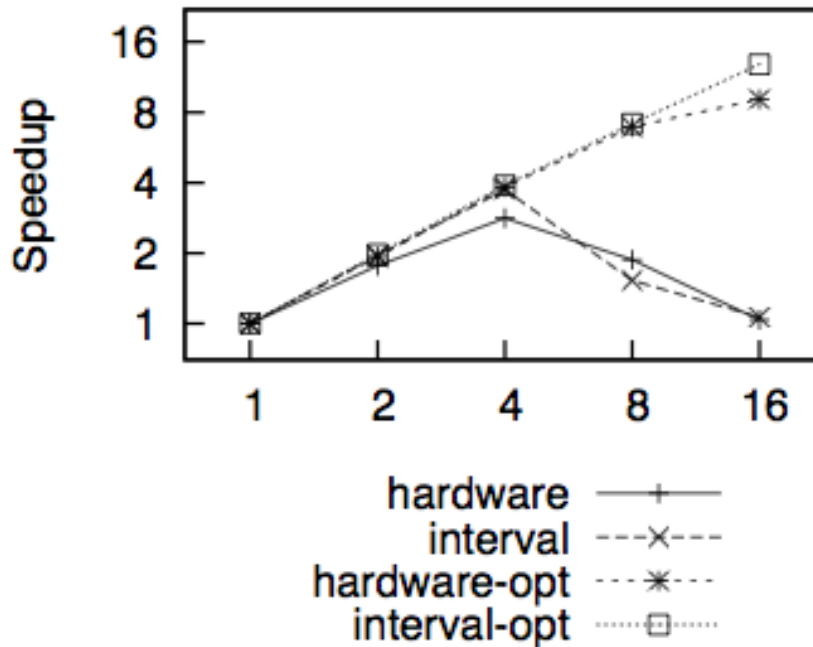
Relaxed synchronization may compromise accuracy

Analyze performance bottlenecks

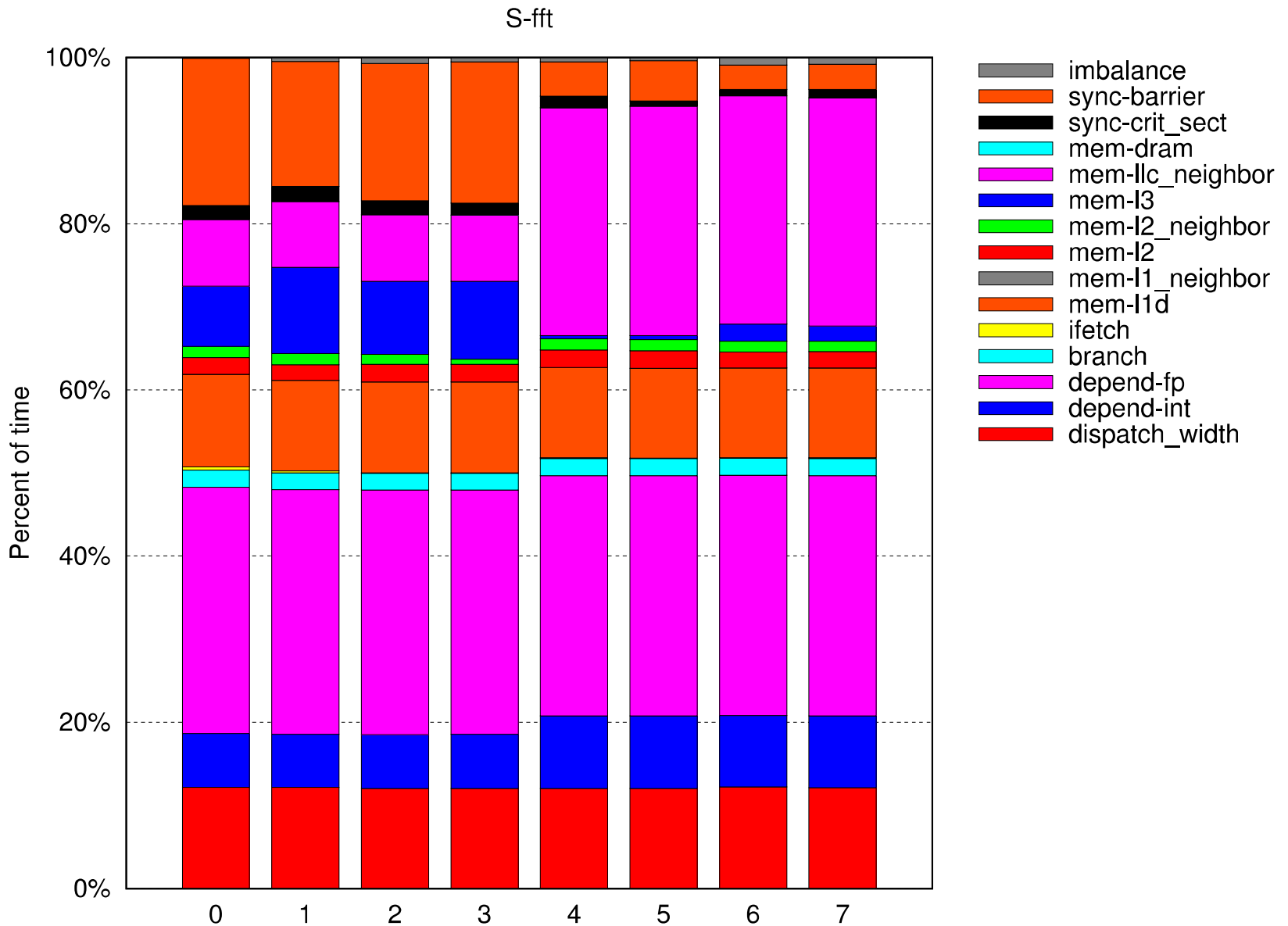


Suggest application improvements

pthread_mutex -> lock inc



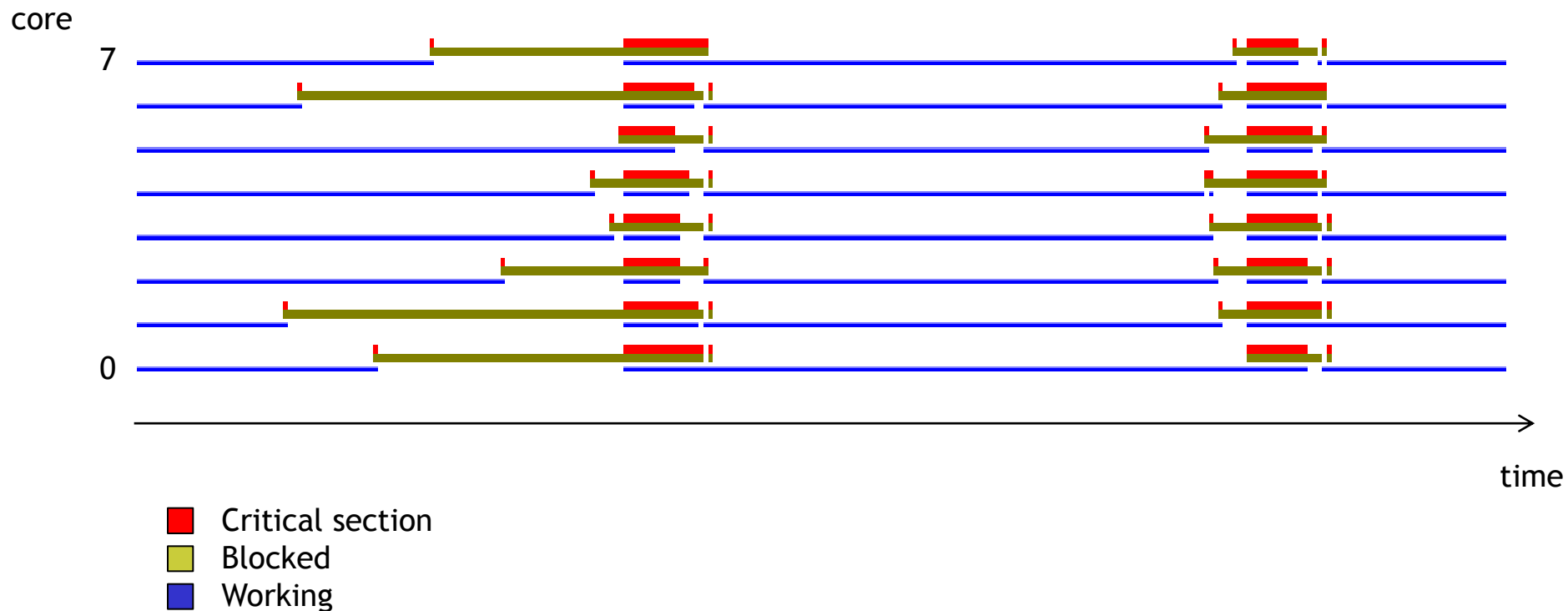
Homogeneous applications?



Analyze synchronization behavior

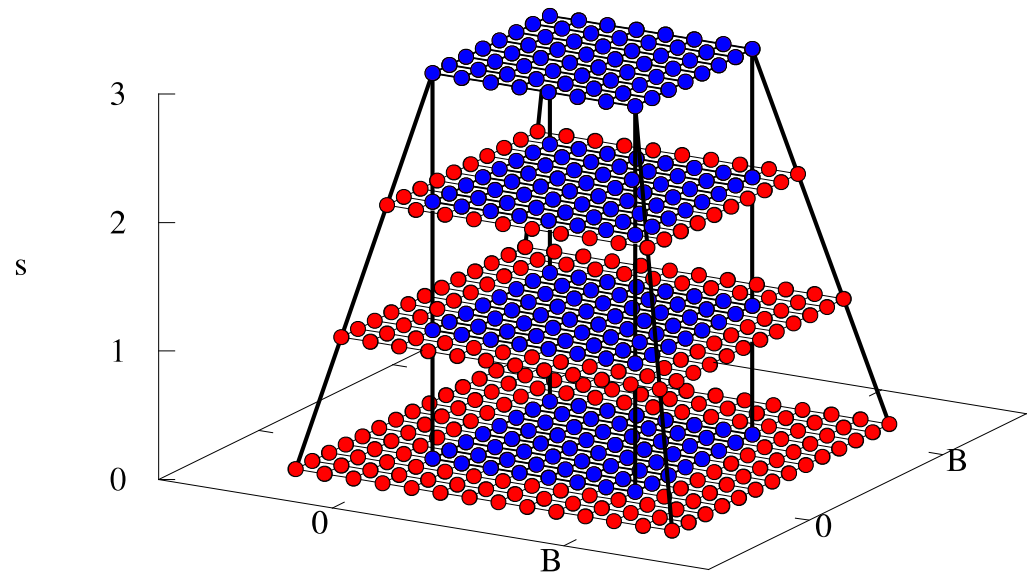
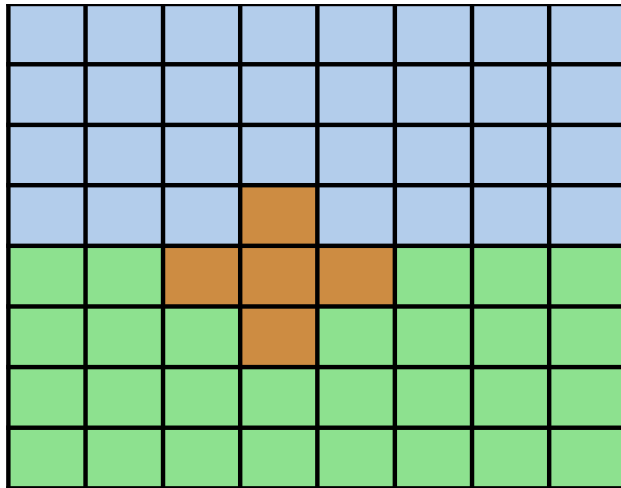
Thread-state timeline for *barnes*:

synchronization, critical sections, load imbalance

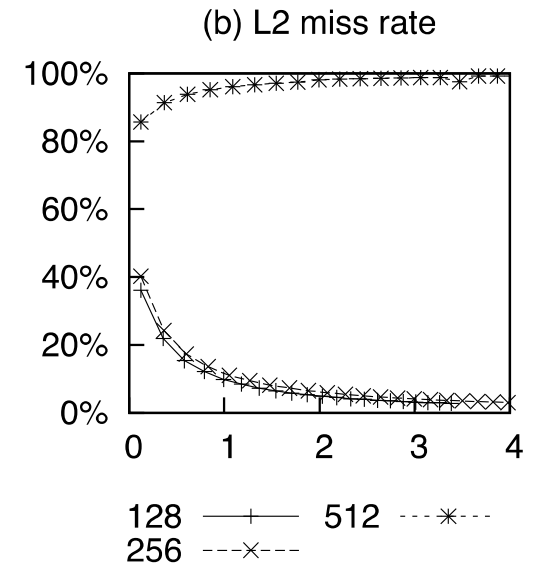
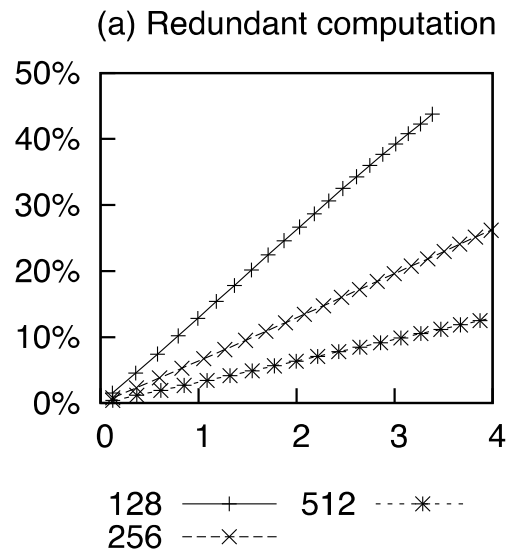
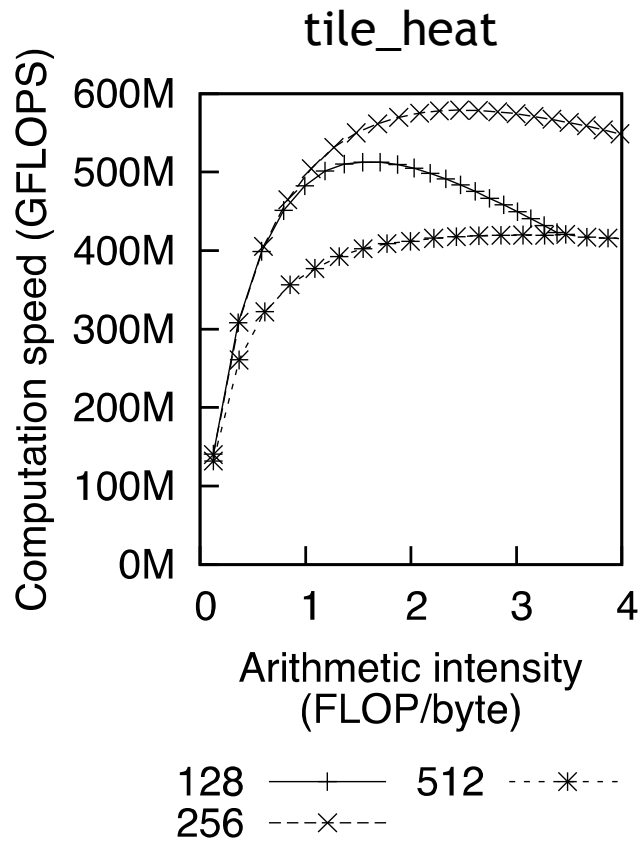


Case study: tiled heat transfer

- 5-point stencil, applied to consecutive time steps
- Optimization: tiled to optimize locality, multiple time steps per tile – but requires redundant computation at tile edges



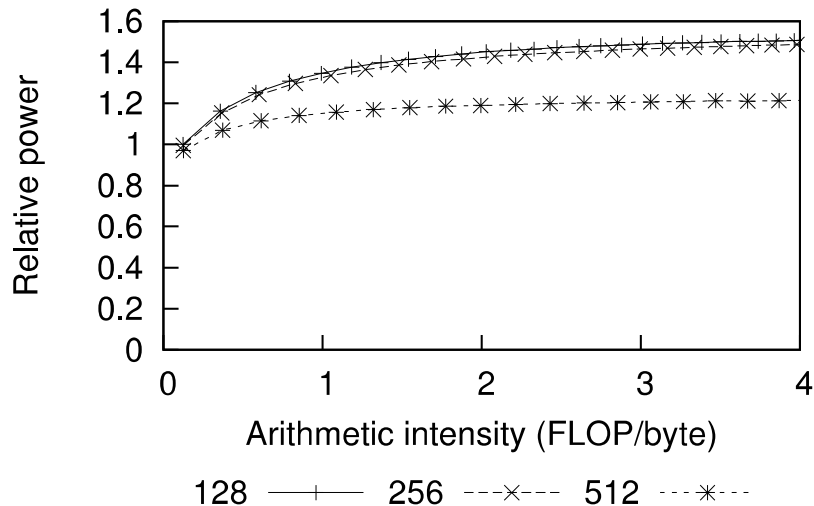
Tile size and steps vs. cache behavior



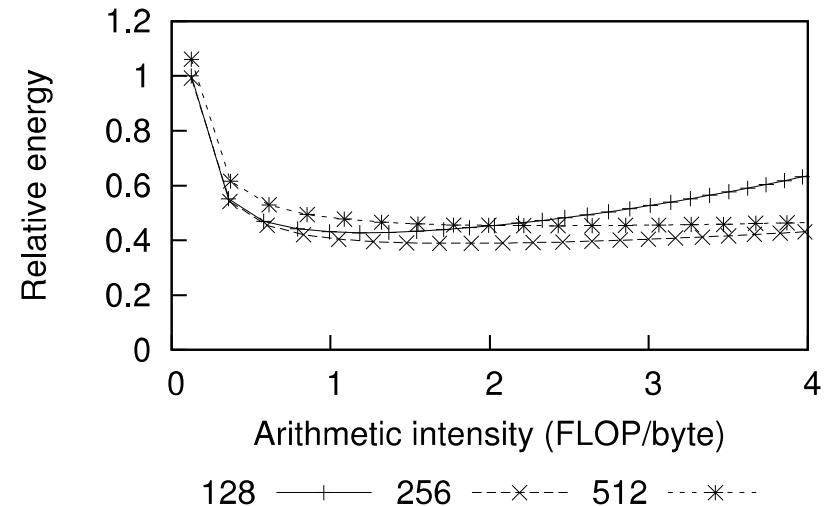
Not just time, energy as well

Integration with McPAT, provide application-specific estimates for power, energy (and EDP, ED²P, ...)

(a) Power

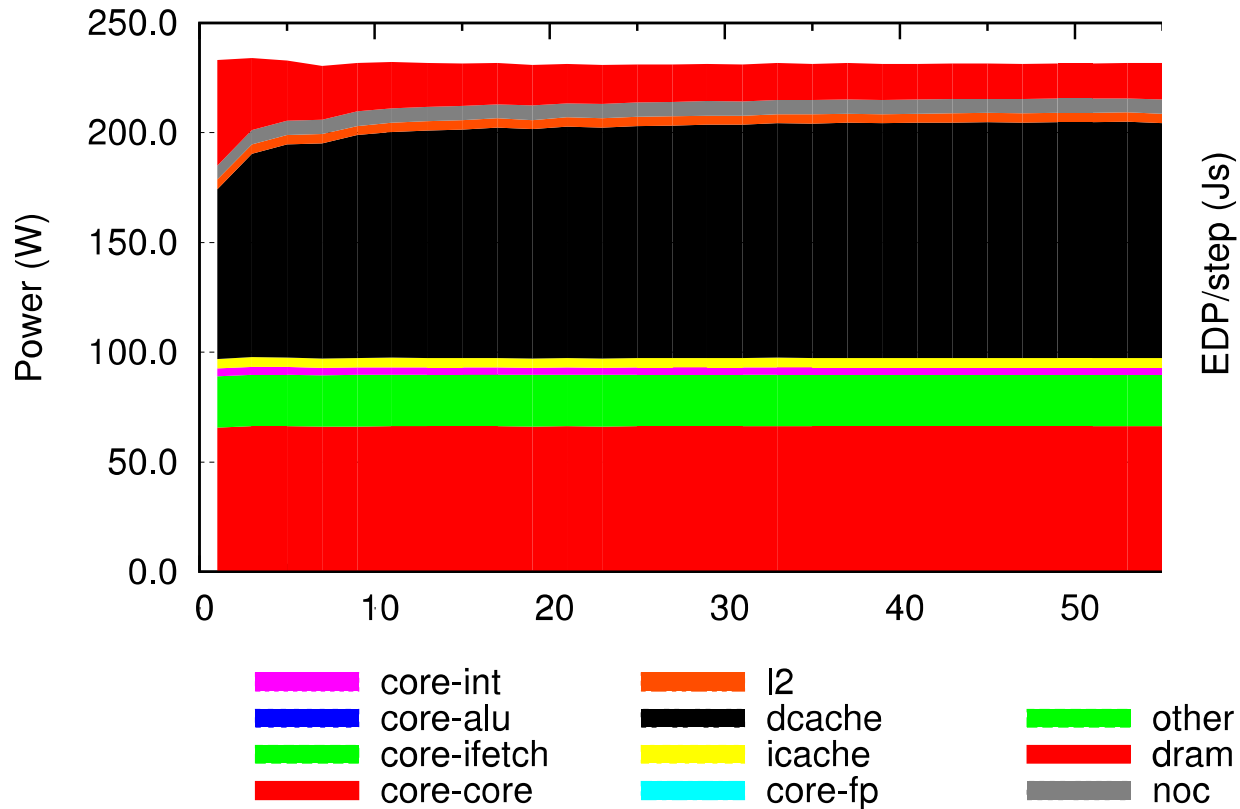


(b) Energy per step

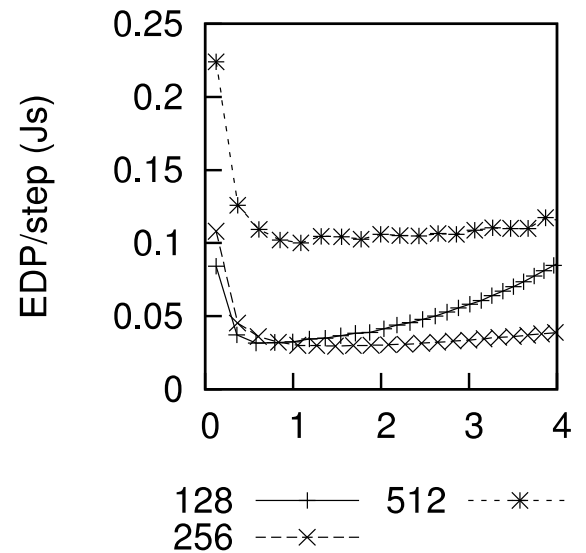


Where is the energy going?

16 cores, tilesize = 256



EDP - 16 cores

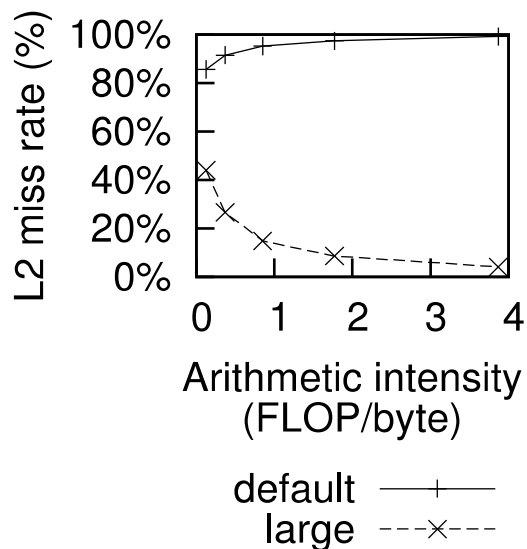


EDP: Energy Delay Product

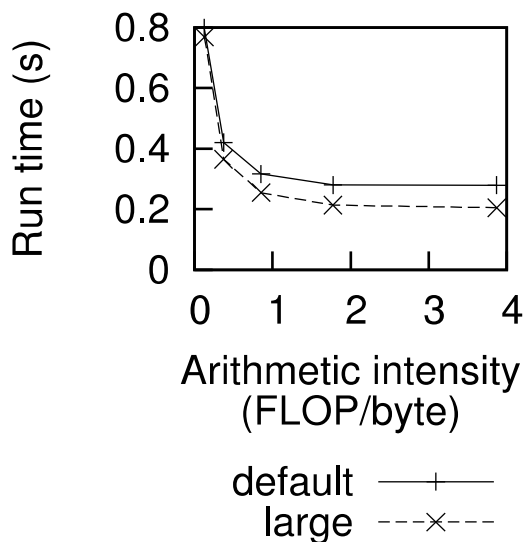
Architectural exploration

Experiment: double the size of L2 and L3 caches

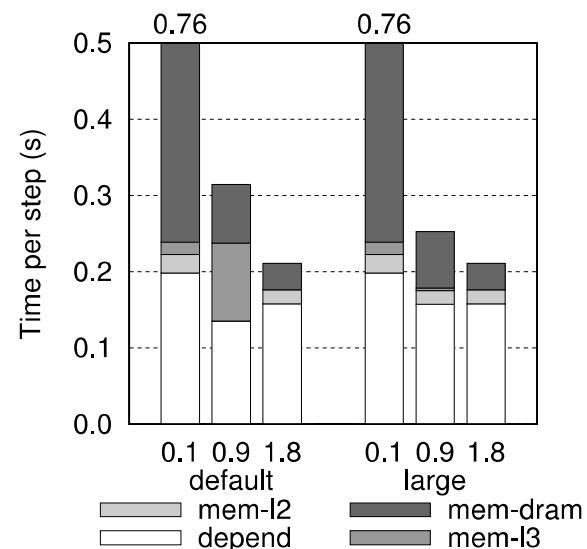
(a) L2 cache miss rate



(b) Run time per step



(c) Time stack



Conclusions

- Sniper is a fast and accurate simulation for multicore processors
- Useful both for hardware and software designers
- Faster than most simulators, so Sniper can be used to model the effects of large caches, large input sets, multiple runs
- More accurate than instrumentation (no intrusion), higher visibility
- Allows for architectural exploration (vs. performance counters)



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